

Probabilistic Connectivity of Random Graphs and Their Unions

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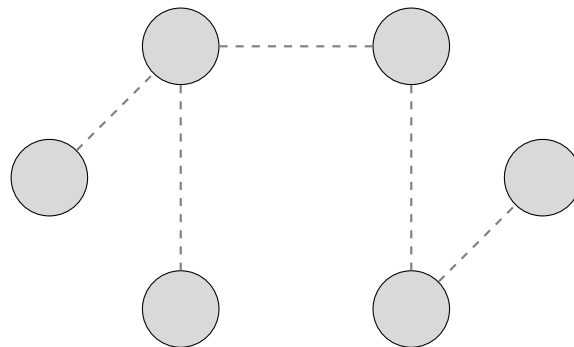
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Why Study Random Graphs?

- 1 Adversaries can jam communications, which makes them unpredictable
- 2 Congested bandwidth makes information flow intermittent
- 3 Randomness encodes the lack of control over these events



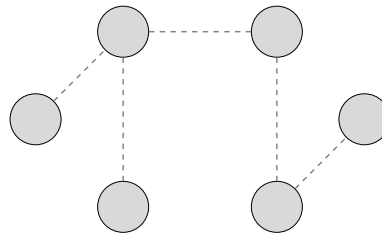
Fundamental Goal

Understand when “enough” information flows for a team of autonomous agents to collaborate.

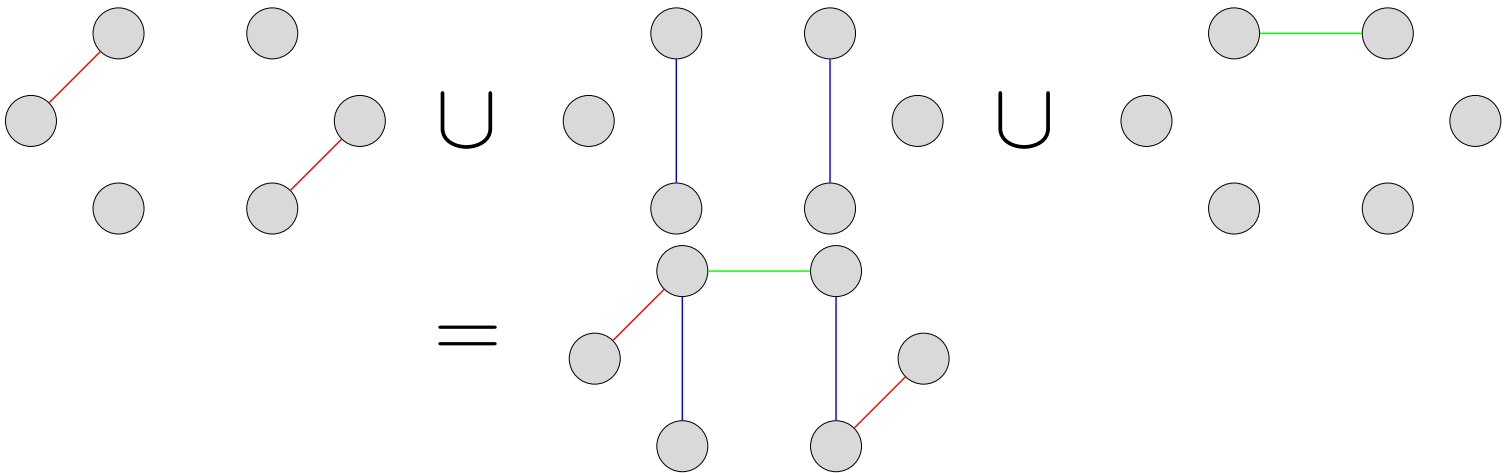


Time-Varying Graphs are Common

- ▶ With autonomous agents, communication graphs may look like



- ▶ No single graph is connected, but their union is





How to Make Connected Unions of Graphs?

Common Assumption

There exists an N such that $\bigcup_{k=t+1}^{t+N} G(k)$ is connected for any t .

- ▶ This lets autonomous agents
 - 1 Rendezvous
 - 2 Assemble formations
 - 3 Solve optimization problems
- ▶ The value of N tells us how quickly we do these, relates the flow of information to performance

Mathematical Question

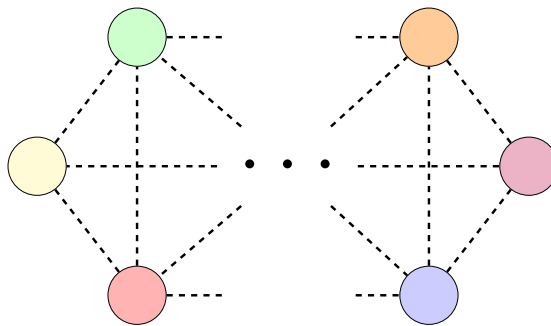
Q: What is the probability that a specific union is connected?

A: $\mathbb{P} \left[\bigcup_{k=t+1}^{t+N} G(k) \text{ connected} \right] \geq f(\text{graph parameters})$

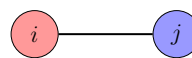


Erdős-Rényi Graphs

- ▶ Defined by parameters $n \in \mathbb{N}$ and $p \in (0, 1)$
- ▶ Graphs are on n nodes:



- ▶ Each edge appears with probability p :

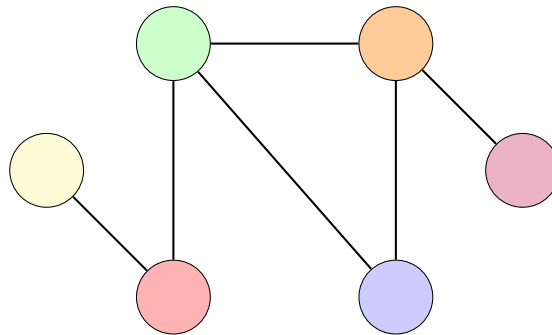
 with probability p

 with probability $1 - p$



New Analyses Required for Multi-Agent Systems

- ▶ We require innovations beyond the existing literature:
 - ▶ Common to take $\#nodes \rightarrow \infty$, but we have small networks
 - ▶ The standard Erdős-Rényi model includes all edges, but we won't have that



- ▶ We also avoid assuming $p \sim \frac{\log n}{n}$ or $p = f(n)$ because p is outside our control

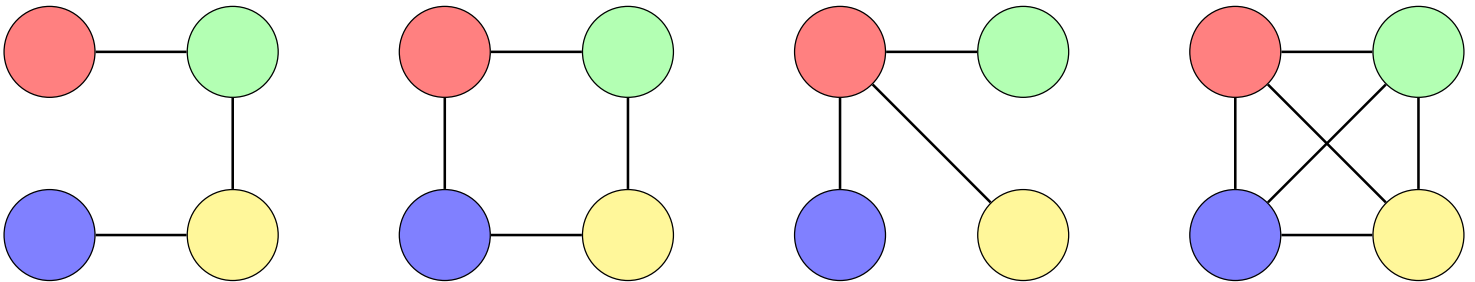


We Study Graphs using Algebraic Connectivity

- ▶ Define $L = D - A$, and denote its i^{th} eigenvalue by $\lambda_i(L)$
- ▶ A classic result says G is connected if and only if $\lambda_2(L) > 0$
- ▶ What is

$$\mathbb{P} \left[\lambda_2 \left(L \left(\bigcup_{k=t+1}^{t+N} G(k) \right) \right) > 0 \right] ?$$

- ▶ We don't prioritize any graph

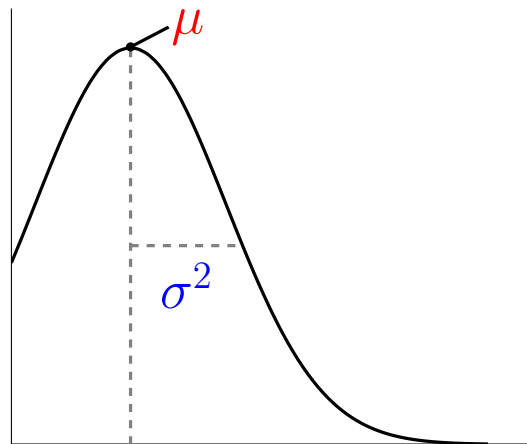




Working on Question 2

- ▶ Applying the Paley-Zygmund inequality, we find

$$\mathbb{P}[\lambda_2(L) > 0] \geq \frac{\mathbb{E}[\lambda_2(L)]^2}{\mathbb{E}[\lambda_2^2(L)]}$$



- ▶ Plan:

- 1 Upper bound $\mathbb{E}[\lambda_2^2(L)]$
- 2 Lower bound $\mathbb{E}[\lambda_2(L)]^2$



Bounding $\mathbb{E}[\lambda_2^2(L)]$

- ▶ Let ℓ be a uniformly sampled positive eigenvalue of L
- ▶ Then $\mathbb{E}[\lambda_2^2(L)] \leq \mathbb{E}[\ell^2]$
- ▶ Because of how we sample,

$$\mathbb{E}[\ell^2] = \frac{1}{n-1} \text{tr}(\mathbb{E}[L^2])$$

Lemma: Upper bound on $\mathbb{E}[\lambda_2^2(L)]$

- ▶ For m total possible edges, edge probability p , d_i the possible degree of node i : a union of N random graphs has

$$\mathbb{E}[\lambda_2^2(L)] \leq \frac{4m(1 - (1-p)^N) - 2m(1 - (1-p)^N)^2 + (1 - (1-p)^N) \sum_{i=1}^n d_i^2}{n-1}$$



Bounding $\mathbb{E}[\lambda_2(L)]^2$

- ▶ Now take n uniformly sampled eigenvalues. Let ℓ_n be the smallest
- ▶ Then

$$\mathbb{E}[\lambda_2(L)] \geq \left(1 - \left(\frac{n-2}{n-1}\right)^{n-1}\right)^{-1} \left[\mathbb{E}[\ell_n] - \frac{2m(1 - (1-p)^N)}{n-2} \left(\frac{n-2}{n-1}\right)^n \right]$$

Lemma: Lower bound on $\mathbb{E}[\lambda_2(L)]$

- ▶ For n nodes, edge probability p , m total possible edges, agent i with possible degree d_i : a union of N random graphs has $\hat{p}(N) = 1 - (1-p)^N$ and

$$\mathbb{E}[\lambda_2] \geq \max \left\{ 0, \left(1 - \left(\frac{n-2}{n-1}\right)^{n-1}\right)^{-1} \left[\frac{2m\hat{p}(N)}{n-1} \left(1 - \left(\frac{n-2}{n-1}\right)^{n-1}\right) - \frac{1}{n-1} \left(2m\hat{p}(N)(n-1)(2 - \hat{p}(N)) + \hat{p}(N)^2(n-1) \sum_{i=1}^n d_i^2 - 4m^2\hat{p}(N)^2 \right)^{1/2} \right] \right\}$$



Main Results: Connected Random Graphs

Theorem: Random Graphs

For n nodes, m possible edges, probability p , agent i 's degree d_i : a union of N random graphs has $\hat{p}(N) = 1 - (1 - p)^N$ and

$$\mathbb{P}[\lambda_2(L) > 0] \geq$$

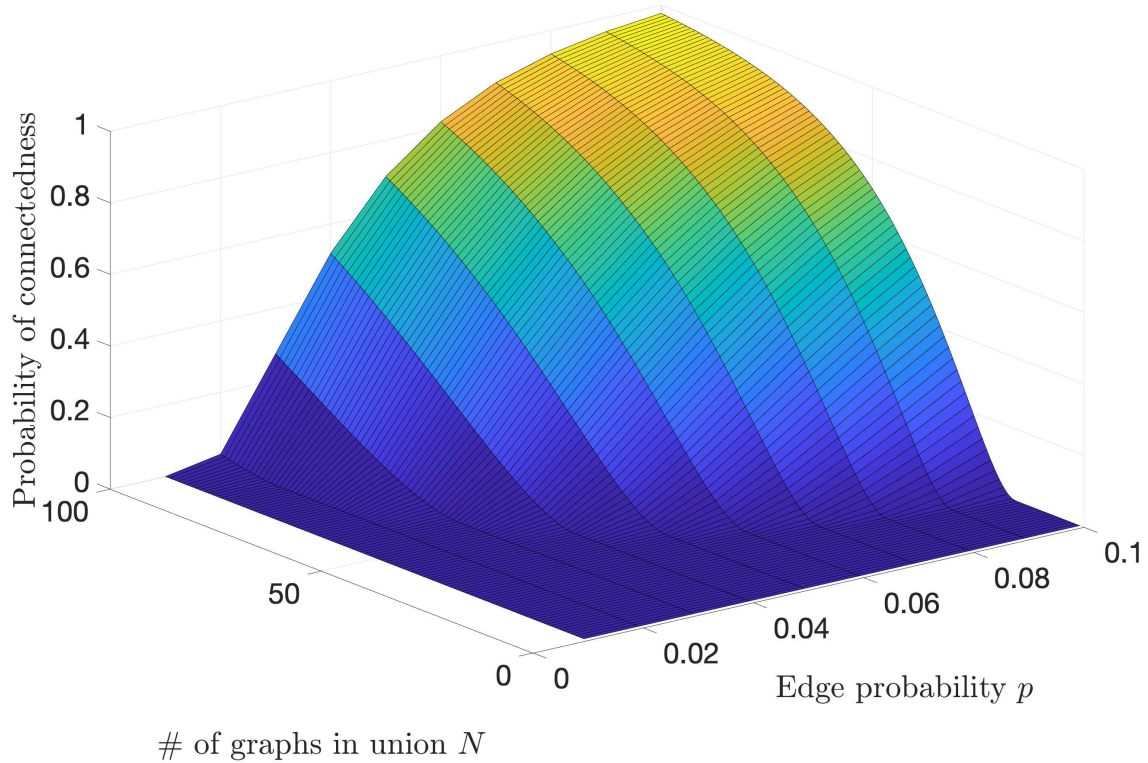
$$\frac{\left(\max \left\{ 0, 2m\hat{p}(N) \left(1 - \left(\frac{n-2}{n-1} \right)^{n-1} \right) - S(m, n, \hat{p}(N), \{d_i\}_{i \in [n]}) \sqrt{n-1} \right\} \right)^2}{(n-1) \left(1 - \left(\frac{n-2}{n-1} \right)^{n-1} \right)^2 (4m\hat{p}(N) - 2m\hat{p}(N)^2 + \hat{p}(N)^2 \sum_{i=1}^n d_i^2)}$$

$$S(m, n, \hat{p}(N), \{d_i\}_{i \in [n]}) = \sqrt{2m\hat{p}(N)(n-1)(2 - \hat{p}(N)) + \hat{p}(N)^2(n-1) \sum_{i=1}^n d_i^2 - 4m^2\hat{p}(N)^2}$$



Numerical Results

- ▶ Consider $n = 20$ agents, vary p and N





Next Steps

- ▶ Formalize tradeoffs between locomotion, communication and performance:
 - ▶ When is it worth it to move to improve comms?
 - ▶ What balance of communication and motion best uses limited energy?
- ▶ Assess vulnerability to attacks on comms:
 - ▶ How bad can comms get before performance is unacceptable?
 - ▶ How close are we to failing to complete our task?



Thank you

