

# Cybersecurity and Privacy in Space and Associated Domains: Update





# Space is a Contested Environment

Many aspects of the space infrastructure need to be considered from a security perspective

*The New York Times*



## *U.S. Warns Allies Russia Could Put a Nuclear Weapon Into Orbit This Year*

The American assessments are divided, however, and President Vladimir Putin denied having such an intention, saying that Russia was “categorically against” it.

## *Russia, in New Push, Increasingly Disrupts Ukraine’s Starlink Service*

Russia has deployed advanced tech to interfere with Elon Musk’s satellite internet service, Ukrainian officials said, leading to more outages on the northern front battle line.



# Recent Research in Space Security

## Don't Shoot the Messenger: Localization Prevention of Satellite Internet Users

Communication &  
Network security

The Dark Side of Scale: Insecurity of Direct-to-Cell Satellite Mega-Constellations

System security

Orbital Shield: Rethinking Satellite Security in the  
Commercial Off-the-Shelf Era



# Recent Work in Related Areas

- Preliminary discussion of privacy-preserving computing for satellites ([AIAA SciTech Forum'24](#))
- Directed energy (acoustic) attacks in underwater environments ([IEEE S&P'24](#))
- Resilience of terrestrial communication infrastructure:
  - Overprivilege in 5G network functions ([ACM WiSec'24](#))
  - Randomness and cryptography failures in 5G network cores ([ACM CODASPY'24](#))
  - Fuzzing of cellular cores and RAN interfaces ([ACM CCS'24](#))

# Holistically Assessing Privacy-Preserving Satellite Computation for RPO and ISM



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*(In submission)*



# Security in Space

## Segments of Space Security

Space Segment



crosslink

Link Segment

up/downlink



User Segment

Ground Segment

- **Needs for both privacy and security in space**

## IN-SPACE Cybersecurity

- **Growing number of satellites & expanding private sector**
- **Motivates autonomy needs**
- **Rendezvous & Proximity Operations (RPO)**
- **Near-field collision avoidance and characterization**

The Aerospace Corporation, 2019

**General goal:** address security and privacy challenges in satellite rendezvous and proximity operations (RPO) and in-space manufacturing (ISM)

- Examining existing limitations of secure multiparty computation (SMC) in space applications
  - Limited existing research on *space segment* and in-space operation security
- Implementation and evaluation of in-space RPO and ISM algorithms on space-certified hardware
  - Categorized mission scenarios and associated security requirements
  - Detailed adversarial scenarios and solutions
- Feasibility assessment of SMC in RPO/ISM given satellite operational constraints
  - characterize use of SMC protocols considering propagation, transmission, local execution time



# Motivation: RPO

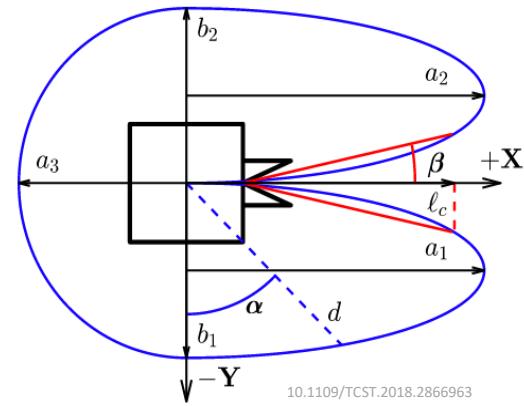
## Rendezvous and Proximity Operations (RPO):

- On-board trajectory operation and replanning
  - E.g. docking, on-orbit servicing/refueling, formation flying
- RPO occurs on-board, autonomously
  - housed in guidance navigation and control (GNC) unit
- Needed at scales of < 500km between satellites

## Ground station vs On-board Control

	Ground station	On-Board
Distance between satellites	1-10 Mm	< 500 km
Time needed	Days-weeks	< 1 day
Speed	km /sec	m /sec
Approach	conjunction analysis	RPO

RPO example: docking



10.1109/TCST.2018.2866963



# Problem: Capability Inference

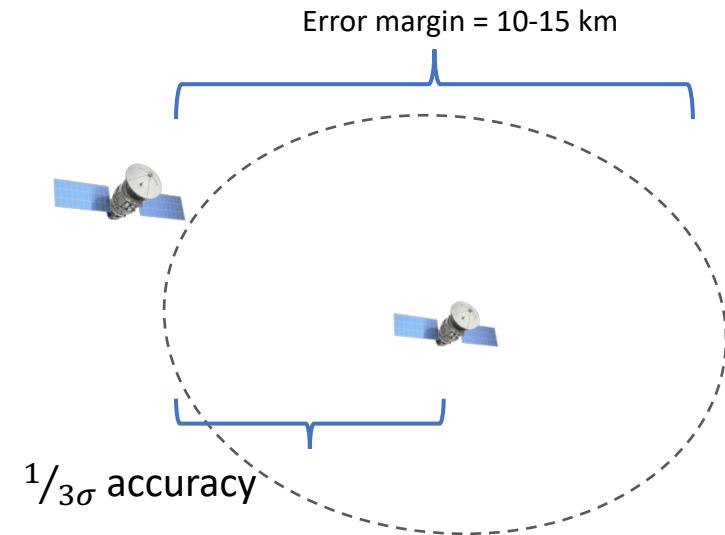
## Example: Collision Avoidance in RPO

- Minimum data to share with other satellites
  - position, velocity, **covariance**



### Stochastic systems

- Probabilistic, not deterministic
- Covariance matrices = quantify uncertainty
  - Calculated using intrinsic sensor variance
- Measure of TRUST, decisions based on accuracy



→ **Problem:** knowledge of error margins (covariance matrices) can lead to inferences on satellite capabilities, purpose, etc. through knowledge of sensors on board



# Motivation: In-Space Manufacturing

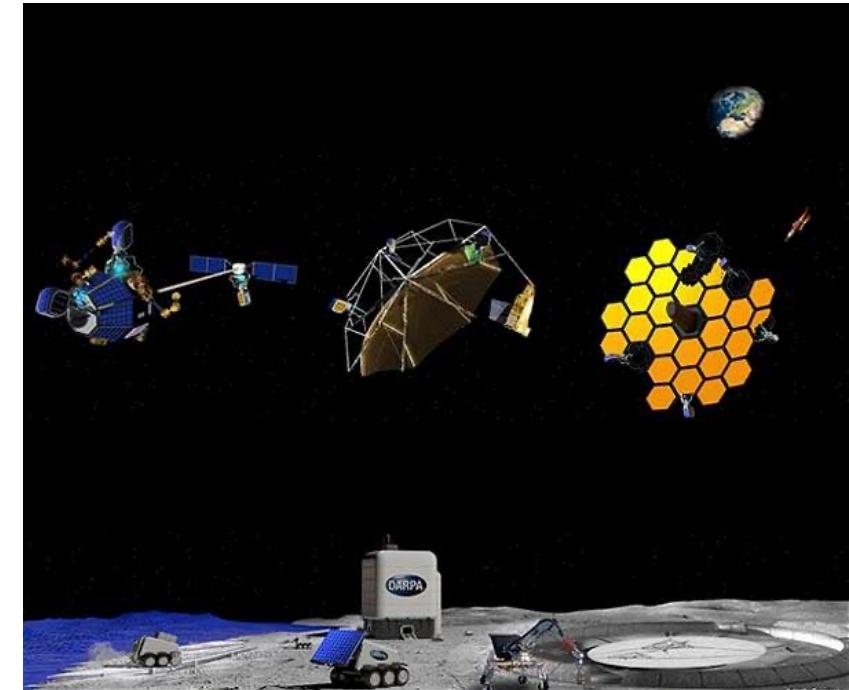
## Example: In-Space Manufacturing

- Integrated circuits, advanced materials, bioengineering, large assembly (Luvoir telescope)

Sensitive Values*	Threat Assumptions
Covariance matrices	Infer proprietary sensor info
Fuel levels	May infer satellite capacity/mission objectives
State-of-health telemetry (e.g. power, heat use)	Infer propulsion system,
Installation/servicing technology parameters	Infer IP (e.g. IC design, robotic arm capability)

\*not exhaustive list, values are mission dependent

→ **Solution:** protect sensitive values using privacy-preserving computation



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# Privacy-Preserving Computation

## Privacy-Preserving Computation (PPC)

- Allows for data to remain encrypted during computation
- Protects **physical integrity** of satellite during RPO and **data privacy** keeping data encrypted

## Secure Multiparty Computation (SMC):

- Cryptographic protocol that allows set of mutually-distrusting parties to jointly compute a function on their inputs, without revealing information about inputs (millionaire's problem)
  1. *2-Party Computation (2PC)*: e.g. Yao's garbled or BMR, binary circuit representation
  2. *Secret sharing*: 3+ parties, arithmetic circuit representation



# Secure Multiparty Computation Tool

## Security Models

- Honest vs. dishonest majority – assumption of behavior of parties
- Semi-honest vs. malicious corruption – passive vs. active adversary

## Computation Domain

Mathematical structure of secret info

- Usually ring structure defined by integer operation with modulus or Galois (finite) field
- Binary circuits or arithmetic circuits
  - Mod prime, mod power 2

## Underlying Primitives

- Secret Sharing
- Garbled Circuits
- Oblivious Transfer
- Homomorphic Encryption

Security model	Mod prime / GF( $2^n$ )	Mod $2^k$	Bin. SS	Garbling
Malicious, dishonest majority	MASCOT / LowGear / HighGear	SPDZ2k	Tiny / Tinier	BMR
Semi-honest, dishonest majority	Semi / Hemi / Temi / Soho	Semi2k	SemiBin	Yao's GC / BMR
Malicious, honest majority	Shamir / Rep3 / PS / SY	Brain / Rep3 / PS / SY	Rep3 / CCD / PS	BMR
Semi-honest, honest majority	Shamir / ATLAS / Rep3	Rep3	Rep3 / CCD	BMR
Malicious, honest supermajority	Rep4	Rep4	Rep4	N/A
Semi-honest, dealer	Dealer	Dealer	Dealer	N/A

Table of supported protocols



# Sharemind vs. MP-SPDZ

Sharemind	MP-SPDZ
Ease of use for industry & non-security professionals	Prominent tool for academic research uses
C++ and proprietary SecreC code	Python
1 SMC approach – linear secret sharing (3+ parties)	Over 30 SMC variants (GC, OT, FHE, SS)
1 security model (semi-honest)	3 security models (semi-honest, malicious, covert)
1 trust option (honest majority)	2 trust options (honest or dishonest majority)
Black box – cannot see or modify source code	White box – can see and modify source code



- MP-SPDZ can execute python code but only at compile time
  - This means we lose access to the large library of python math functions for any values that are secret
- We implemented many custom functions in MP-SPDZ including
  - Eigenvalues and Eigenvector solver
  - Integration Approximation using Simpson's Rule
  - An Error Function Approximation
  - Cross Products

```
def simpsons_rule(f, a, b, n):  
    if n % 2 != 0:  
        raise ValueError("Number of subintervals (n) must be even.")  
    h = (b - a) / n  
    x_values = [a + i * h for i in range(n + 1)]  
    sum = f(a) + f(b)  
    for i in range(1, n, 2):  
        sum += 4 * f(x_values[i])  
    for i in range(2, n-1, 2):  
        sum += 2 * f(x_values[i])  
    sum *= h / 3  
    return sum
```



# Program Selection

- We investigated three programs for test
  - i. Alfano's Algorithm for Conjunction Analysis
  - ii. Artificial Potential Function
  - iii. Quadratic Program

```
P1_inverse = ml.mr(P1,1)
P2_inverse = ml.mr(P2,1)
P3_inverse = ml.mr(P3,1)

M = P1_inverse + P2_inverse + P3_inverse
V = P1_inverse*xhat1 + P2_inverse*xhat2 + P3_inverse*xhat3
M_inverse = ml.mr(M,1)
e = M_inverse*V
```

- We found Alfano's method required higher accuracy for float representations than the default value for MP-SPDZ
  - To achieve accurate results we had to raise the number of bits for the floating point representation
  - This severely impacted the execution time so we excluded Alfano's from our later tests



# Methodology: hardware

## Finding hardware for deployment in space

- Considerations:
  - Commercial off-the-shelf (COTS)
  - Sufficient radiation tolerance
  - Sufficient power & efficiency with limited resources
- Current findings:
  - NVIDIA Jetson Nano boards (ARM processors)



## Emulate satellite cluster

- Prototype with 3 NVIDIA nano boards
- Networked to communicate with each other
- 3 satellites minimum needed for secret sharing



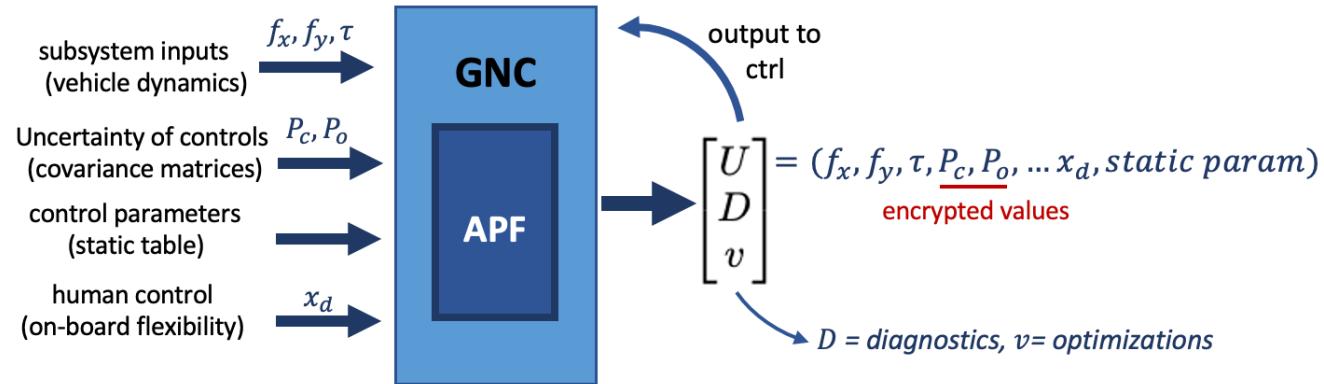
# Algorithm 1: Artificial Potential Function

## Artificial Potential Function (APF): conjunction analysis

- Autonomous Robotic Control algorithm
- Docking, service, collision avoidance
  - On-board trajectory control
- Assume linear orbital dynamics: one satellite stationary relative to other

### Shared parameters

- Control forces :  $f_x, f_y, \tau$  → Public
- Vehicles' covariance:  $P_c, P_o$  → Private

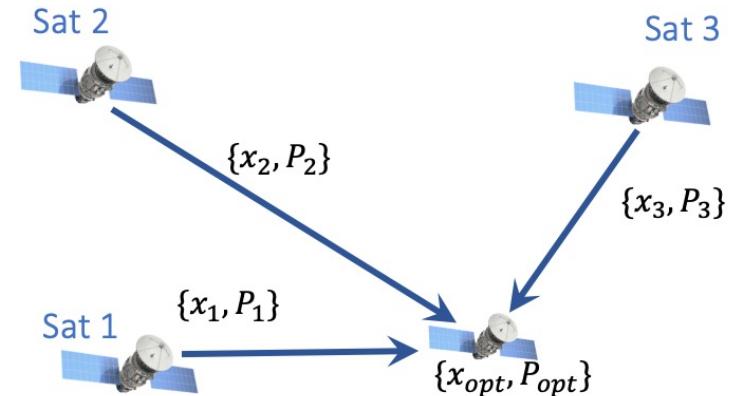
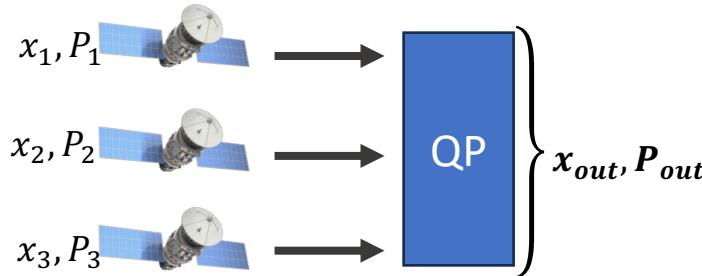




# Algorithm 2: Quadratic Program

## Quadratic Program: multi-point inspection

- Sensor Fusion optimization algorithm
- Need 3+ parties for 3 dimensional accuracy  
(secret sharing or homomorphic encryption)



### Shared parameters

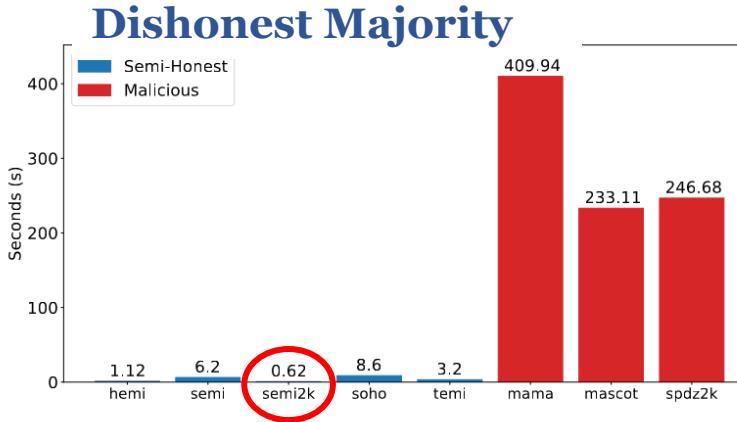
- Measured positions:  $x_1, x_2, x_3$  → Public
- Position covariance:  $P_1, P_2, P_3$  → Private



# Evaluation – APF Initial Benchmarks

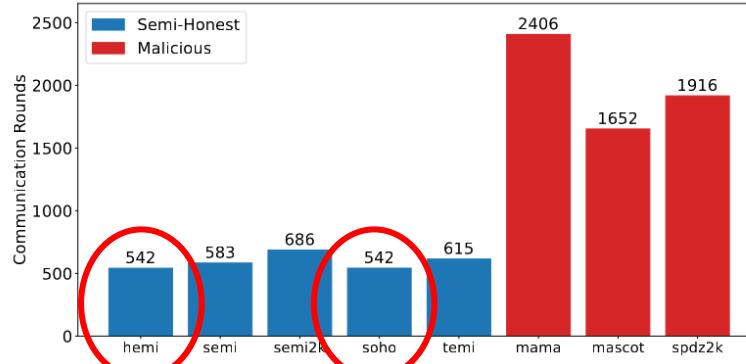
Local execution time

Communication rounds



BEST → semi2k

(a) Execution time comparison for the two-party MPC protocols running APF



BEST → hemi, soho

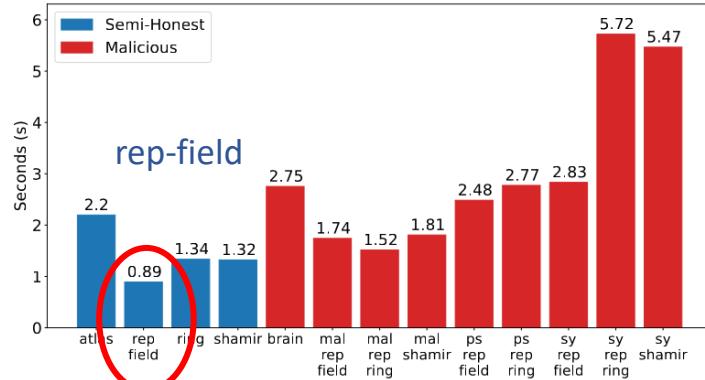
(b) Communication rounds comparison for the two-party MPC protocols running APF



# Evaluation: QP Initial Benchmarks

## Local exec time

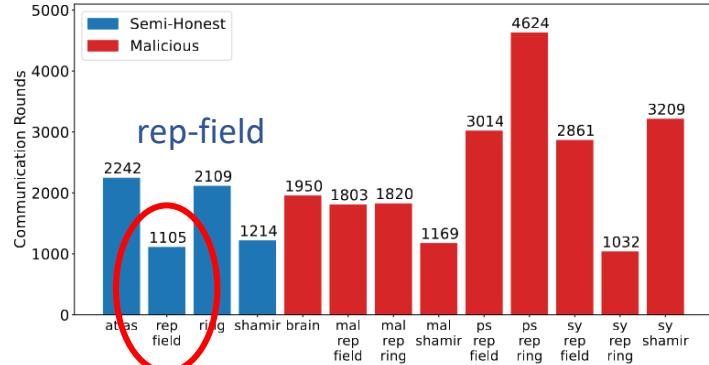
### Honest Majority



(a) Execution time comparison for the honest majority three-party MPC protocols running QP

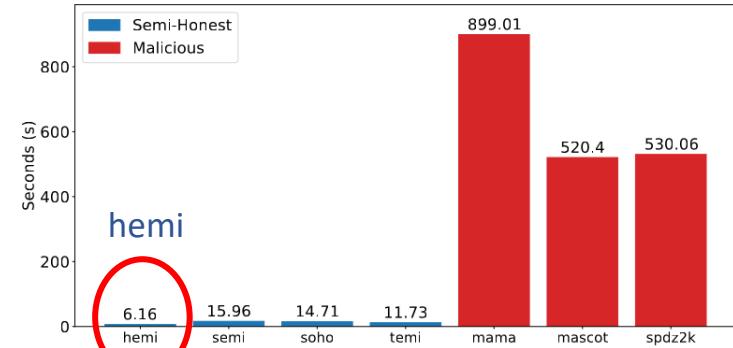
## Comm rounds

### rep-field

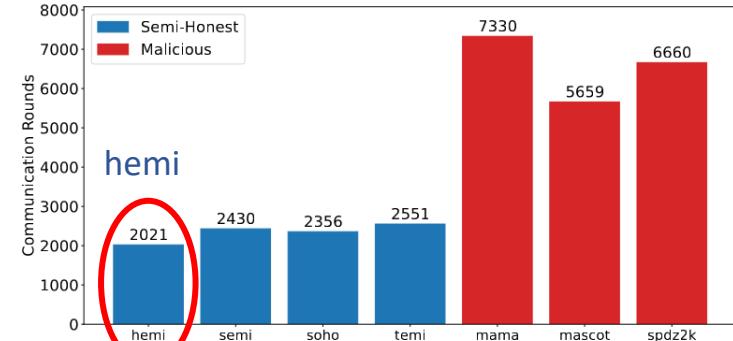


(b) Communication rounds comparison for the honest majority three-party MPC protocols running QP

### Dishonest Majority



(a) Execution time comparison for the dishonest majority three-party MPC protocols running QP



(b) Communication rounds comparison for the dishonest majority three-party MPC protocols running QP



# Total Execution Time

$$t_{tot} = t_{exec} + t_{prop} + t_{trans}$$

The local execution time of the protocol

The propagation time of the signal.

$$t_{prop} = \text{comm rounds} * \frac{500 \text{ km}}{c}$$

The transmission time governed by the radios.

$$t_{trans} = \frac{\text{data overhead (Mb)}}{10 \left( \frac{\text{Mb}}{\text{s}} \right)}$$



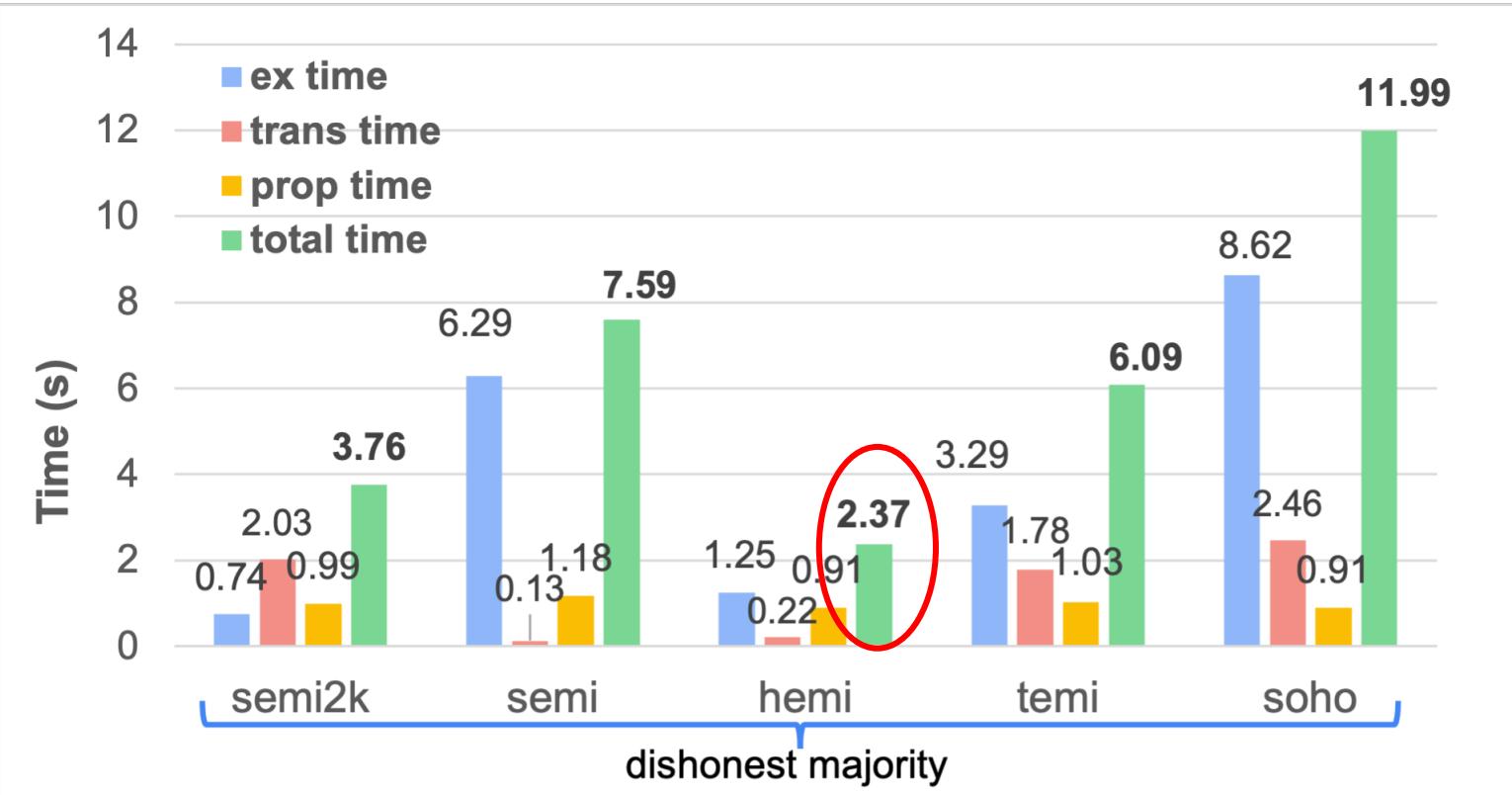
# Evaluation: APF Space Factors

Semi-honest model

Semi2k no longer the most efficient

BEST → hemi

Why?  
Comm rounds





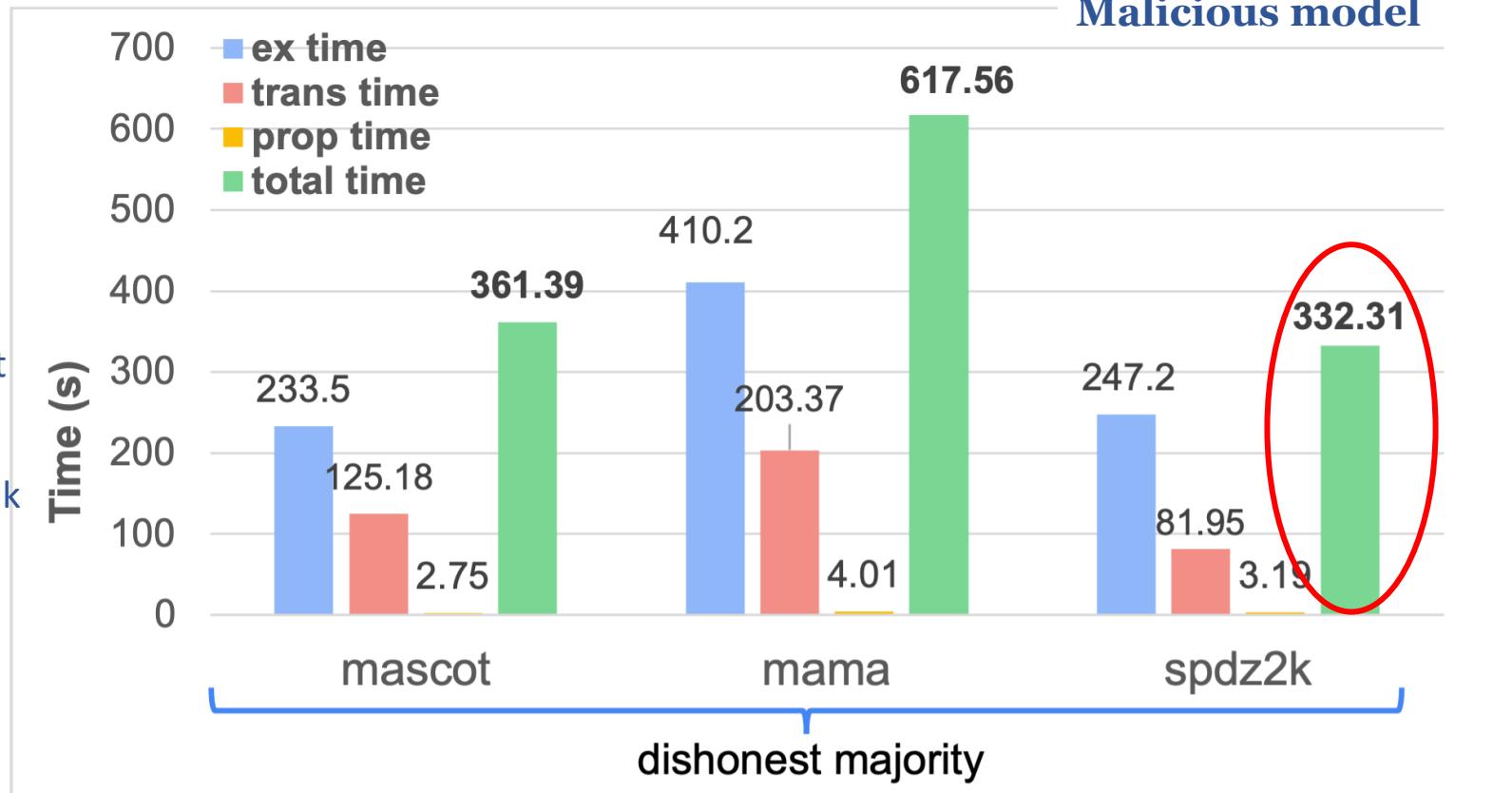
# Evaluation: APF Space Factors

Malicious model

Mascot no  
longer the most  
efficient

BEST → spdz2k

Why?  
Comm rounds



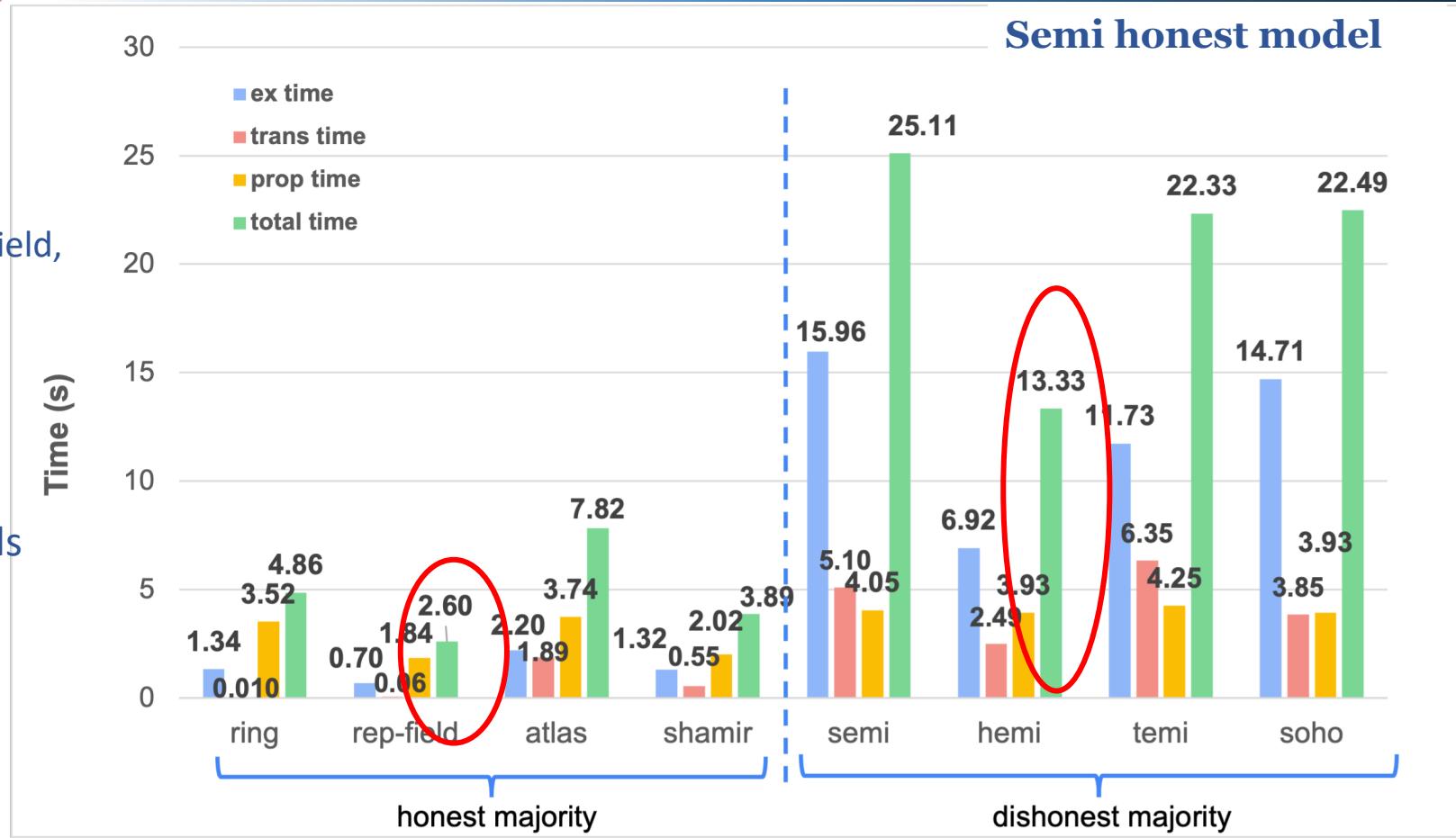


# Evaluation: QP Space Factors

**Semi honest model**

BEST → rep-field,  
hemi

Also lowest  
comm rounds

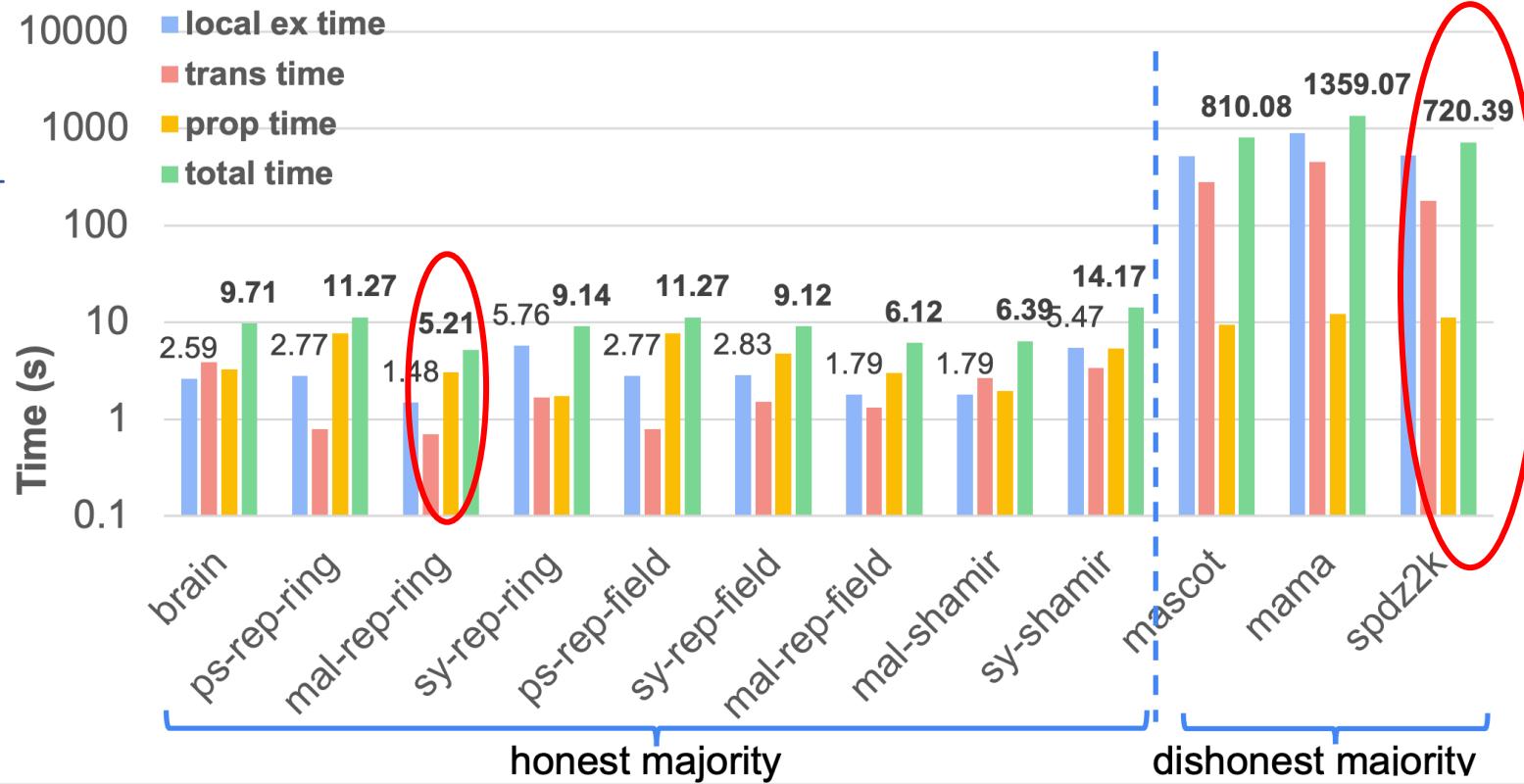




# Evaluation: QP Space Factors

## Malicious model

BEST → mal-rep-ring, spdz2k



## Conclusion:

- Communication rounds play a large role, but not sufficient themselves (sy-rep ring)

### APF Program

Semi-Honest Model, Dishonest Majority	semi	2.05 s
Malicious Model, Dishonest Majority	spdz2k	332 s

### Quadratic Program

Semi-Honest Model, Dishonest Majority	hemi	13.3 s
Malicious Model, Dishonest Majority	spdz2k	720 s
Semi-honest Model, Honest Majority	rep-field	2.6 s
Malicious Model, Honest Majority	mal-rep-ring	5.21 s



## Conclusion:

- Communication rounds play a large role, but not sufficient themselves (sy-rep ring)
- Malicious, dishonest majority protocols may require further optimization to meet certain mission criteria

### APF Program

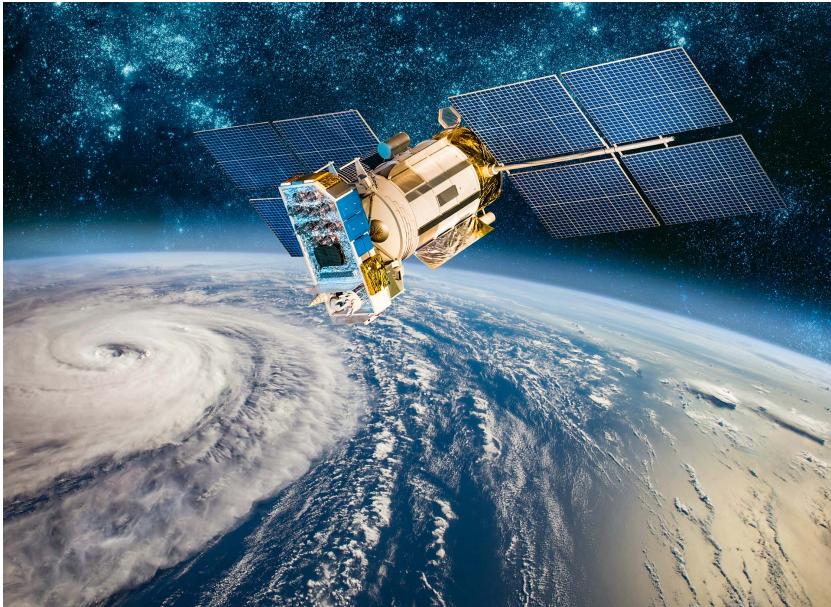
Malicious Model, Dishonest Majority	spdz2k	332 s
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### Quadratic Program

Malicious Model, Dishonest Majority	spdz2k	720 s
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# Current and Future Work



Source: verdict.co.uk

## Current:

- ACSAC '24 Conference paper – in review

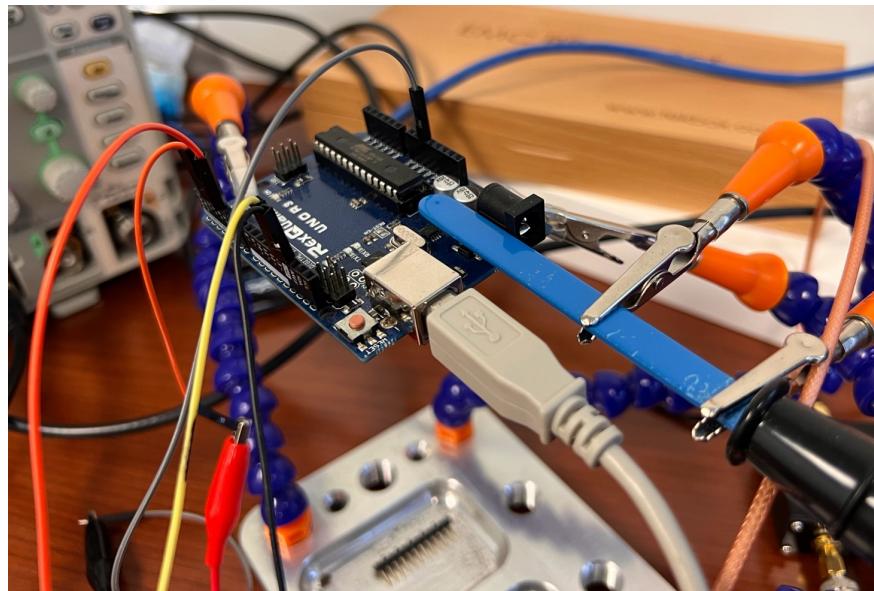
## Future Work:

- Evaluate sensor robustness against EMI injection
- Perform an electromagnetic analysis to validate the correct execution of critical operations on on-board MCUs
- Explore other areas for in-space privacy and security applications



# Current and Future Work

- EM emissions from microprocessors can be used to validate operations in Microcontrollers such as those used to control actuators for thrusters or reaction wheels





# Questions?