

AACOE Updates on Protecting Information and Computation Privacy



Kevin Butler, University of Florida

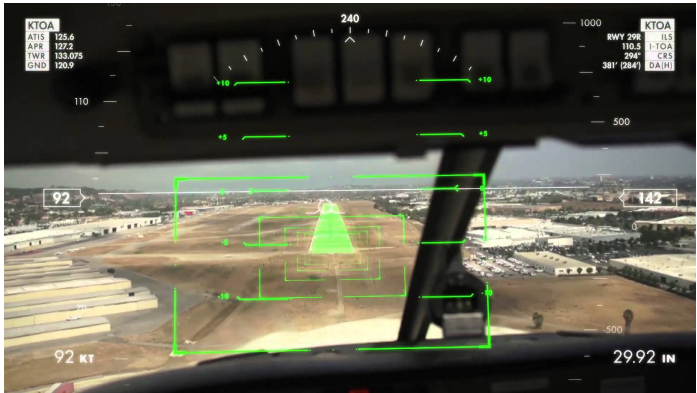
AACOE Program Review

26 April 2023



Human-Machine Interaction

- Current state of deployed UASs involve significant human interaction (\leq L3 autonomy)
- Autonomous systems will potentially learn from simulation data informed by human interaction
- Augmented reality (AR) systems can assist near-term operations while virtual reality (VR) simulators are standard for training
- What risks to privacy are incurred in these systems?





Gaze Datasets:

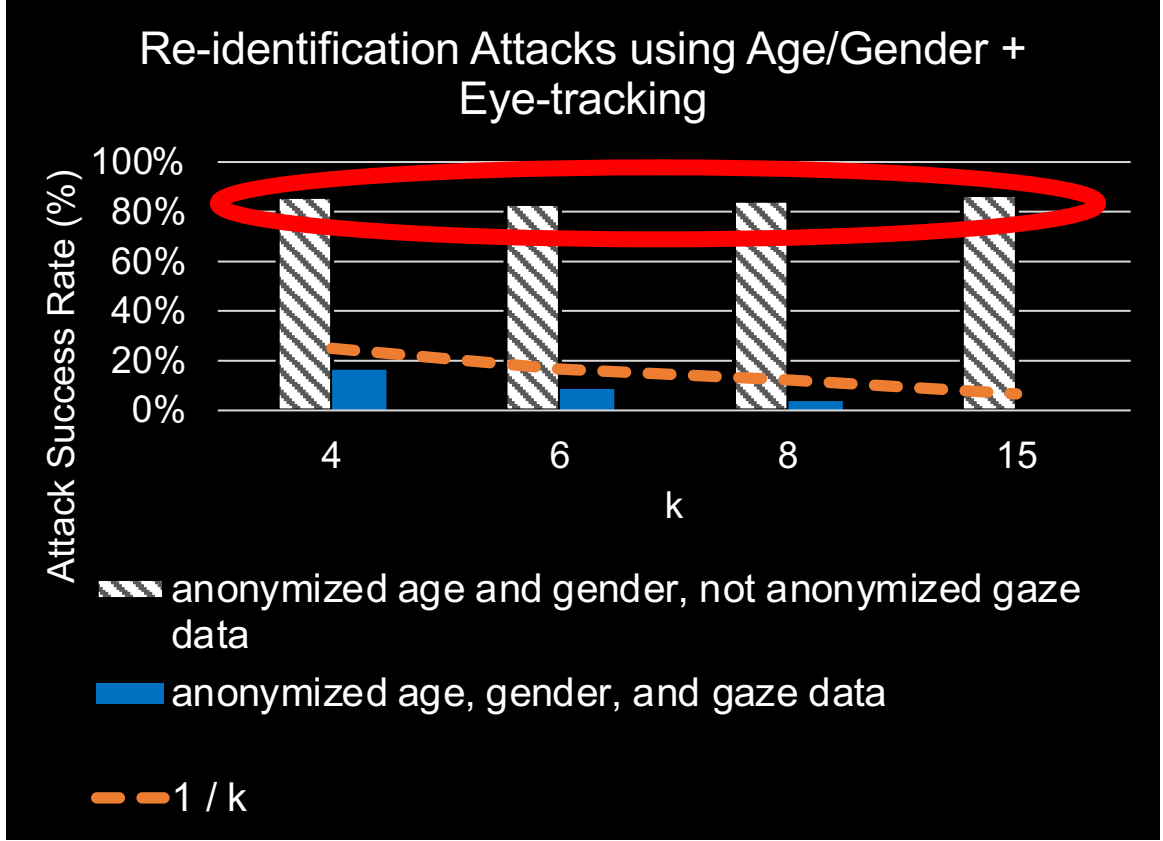
- ET-DK2 (N = 18)
- 360_em (N = 13)

360° VR Viewing

k -anonymity: $1 / k$

Attack Success Rate

- Raw gaze data
- Anonymized gaze data

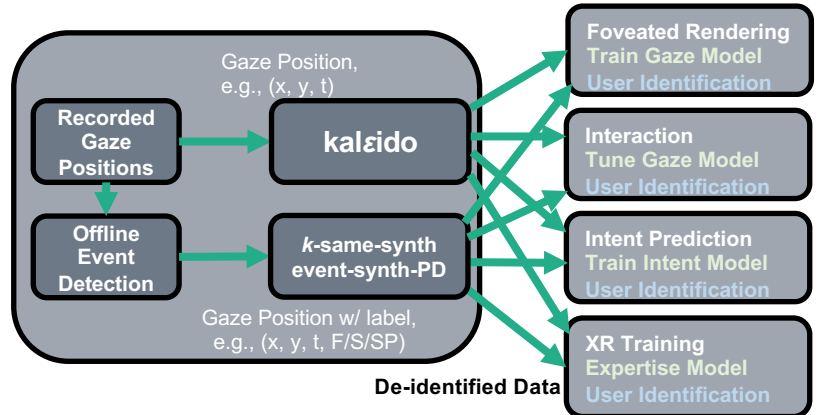
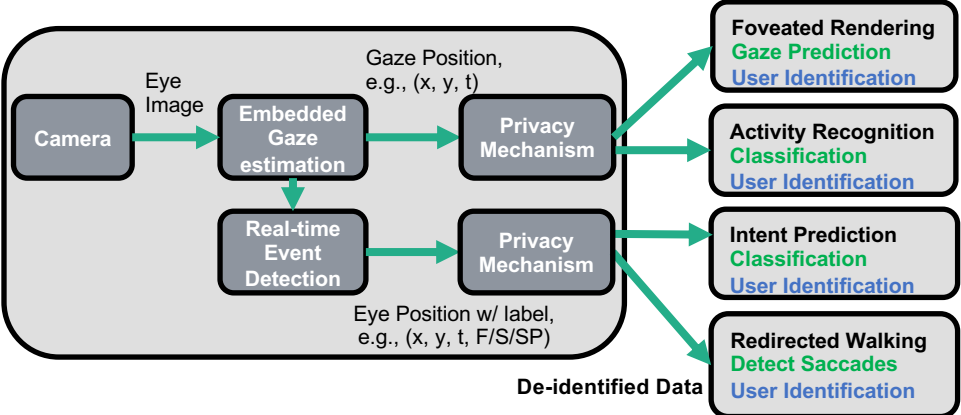




kalaido-DP [Li et al., USENIX 2021]
 Spatial Differential Privacy (DP)
 Can be applied in real-time or to dataset

Past Work: Noisy samples
 Real-time, No Privacy Guarantee

This Work: Synthetic samples
 Dataset, Privacy Guarantee



[David-John et al., TVCG 2021]

[David-John et al., TVCG 2023]





DGaze dataset (N = 43)

Gaze Prediction (100 ms), 3D Scene

Mechanism	Identification Rate (↓)	Runtime (↓)
Raw Data	2%	N/A
<i>k</i> -same synth (ours)	1.1%	52 sec
Event-synth-PD (ours)	1.3%	4 min
kalēido-DP	2.1%	2 min

EHTask dataset (N = 30)

Activity Classification, 360° Video

Mechanism	Identification Rate (↓)	Runtime (↓)
Raw Data	28%	N/A
<i>k</i> -same synth (ours)	7.5%	2 min
Event-synth-PD (ours)	9.2%	15 min
kalēido-DP	6.0%	5 min

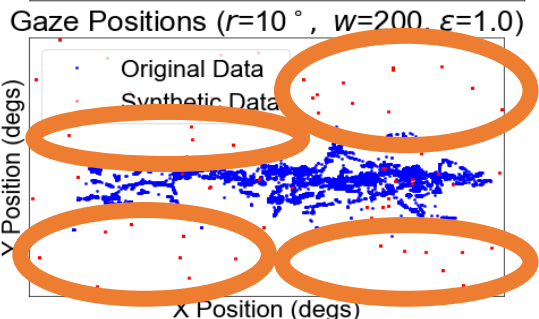
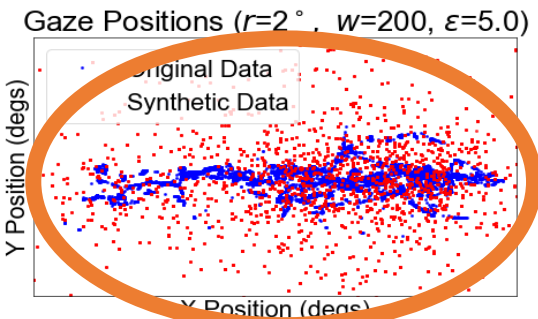
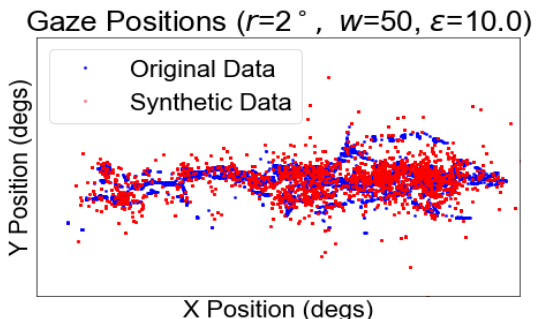
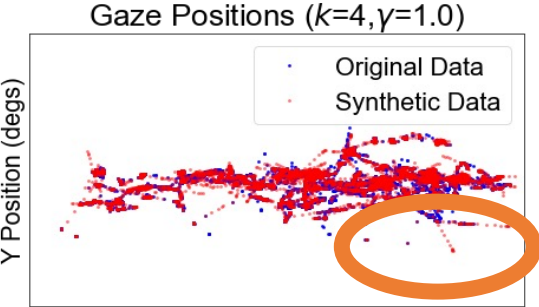
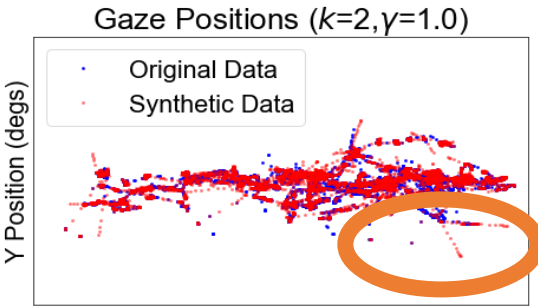
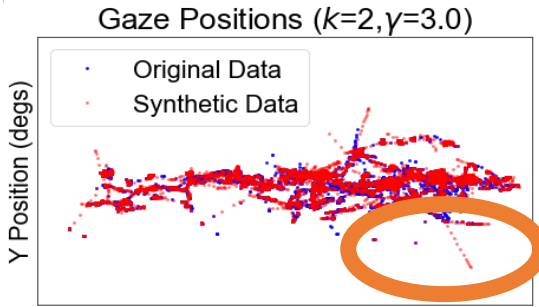
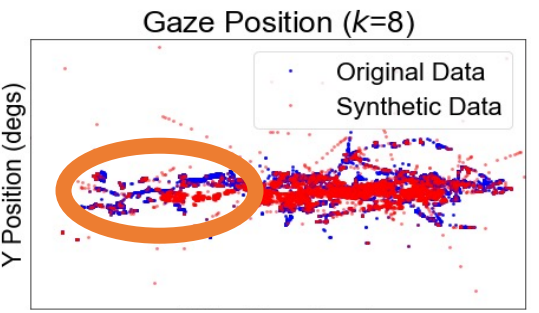
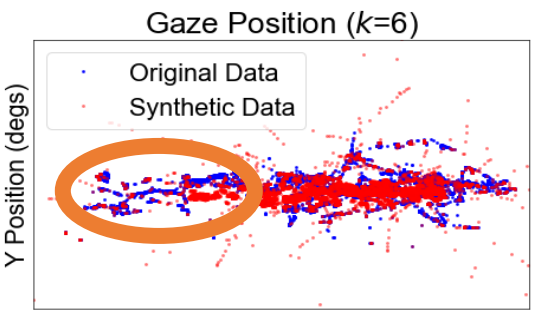
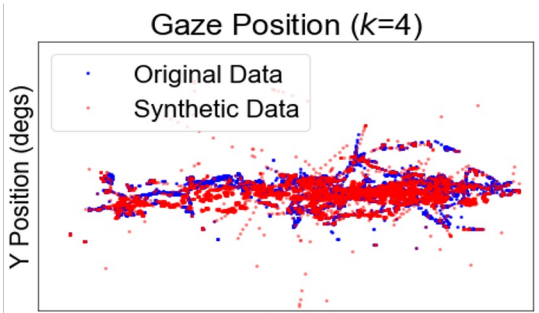


Evaluation of XR Applications

k-same synth
(ours)

Event-synth-PD
(ours)

kaleido-DP

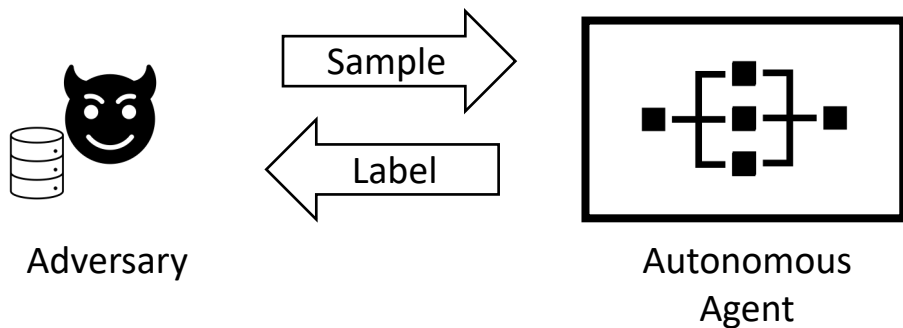




Hard-Label Attacks

Hard-label adversarial machine learning attacks are a “grand-prize”:

- Adversary only needs **query access** to generate “label-flipped” samples (e.g., through compromised user)
- Hard-label attacks are gaining popularity, but not well characterized apart from convergence guarantees.





Subsampling and query efficiency

- Questions we sought to answer:
 - What advantages does search subsampling give the adversary?
 - How can we generalize the idea of search subsampling?
- We addressed this as an information-theoretic problem, leveraging the data processing inequality to derive a close—form solution of manifold-gradient mutual information

$$I(\mathcal{G}, \mathcal{M})_\epsilon = 2 \int_{\mathcal{M}^+} p(1, x^+) \log\left(\frac{p(1, x^+)}{p_{\mathcal{G}}(1)p_{\mathcal{M}}(x^+)}\right) dx^+ + 2 \int_{\mathcal{M}^+} p(-1, x^+) \log\left(\frac{p(-1, x^+)}{p_{\mathcal{G}}(-1)p_{\mathcal{M}}(x^+)}\right) dx^+.$$

$$I(\mathcal{G}, \mathcal{M})_\epsilon = \frac{2}{\sqrt{2\pi\sigma^2}} \sum_{i=1}^{|\mathcal{M}^+|} \exp\left(-\frac{(x_i^* - \theta)^2}{2\sigma^2}\right) \cdot \beta_i^+ \Delta_i + \frac{2}{\sqrt{2\pi\sigma^2}} \sum_{i=1}^{|\mathcal{M}^+|} \exp\left(-\frac{(x_i^* + \theta)^2}{2\sigma^2}\right) \cdot \beta_i^- \Delta_i.$$





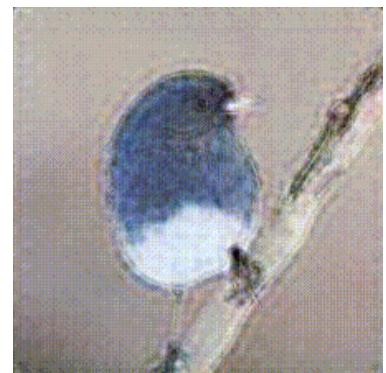
Results of Dimensionality Reduction

HSJA

BiLN+HSJA

AE+Sign-OPT

Adversarial

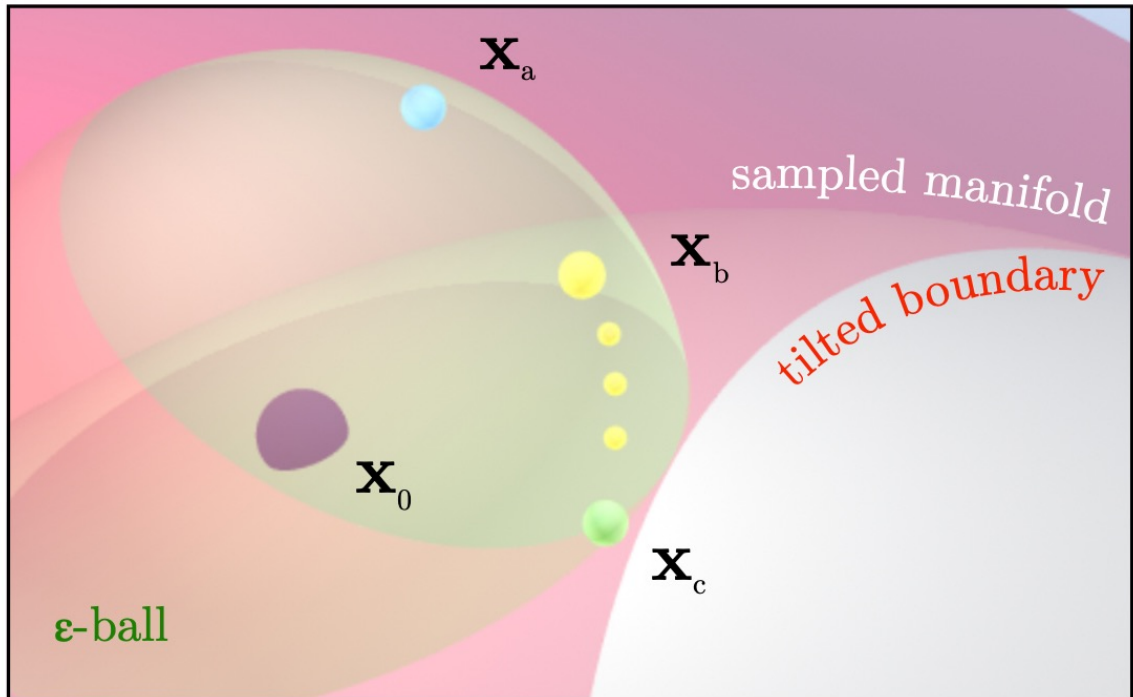


Diff





Geometric Interpretation





Protecting Satellite Proximity Operations via Secure Multi-Party Computation



Caroline Fedele

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26 April 2023

General goal: provide evaluation of secure satellite proximity operations using privacy-preserving computation

Demonstrate use of **secure multiparty computation (SMC)**, a method of operating on encrypted data, allowing **satellite operations** to be conducted between mutually-distrustful agents without leaking information about satellites' capabilities

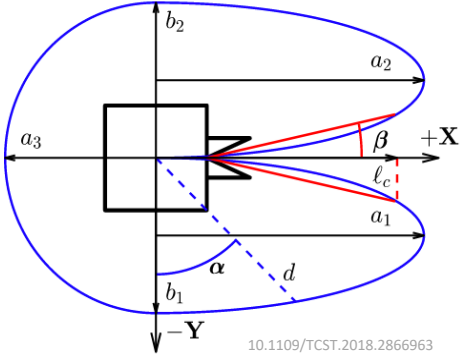
- Investigating existing tools and SMC approaches with which to implement SMC
- Determining relevant problems in space/satellite research where privacy is a concern
- Prototyping SMC setup for satellites on embedded boards for autonomous operations
- Evaluating algorithms with and without SMC: matrix multiplication, RPO algorithms
- Benchmarking overhead added by SMC
- Broader characterization problems



Rendezvous and Proximity Operations (RPO):

- On-board trajectory operation and replanning
 - E.g. docking, on-orbit servicing/refueling, formation flying
- RPO occurs on-board, autonomously
 - housed in guidance navigation and control (GNC) unit
- Needed at scales of < 500km between satellites

RPO example: docking



10.1109/TCST.2018.2866963

Ground station vs On-board Control

	Ground station	On-Board
Distance between satellites	1-10 Mm	< 500 km
Time needed	Days-weeks	< 1 day
Speed	km /sec	m /sec
Approach	conjunction analysis	RPO



Problem: Capability Inference

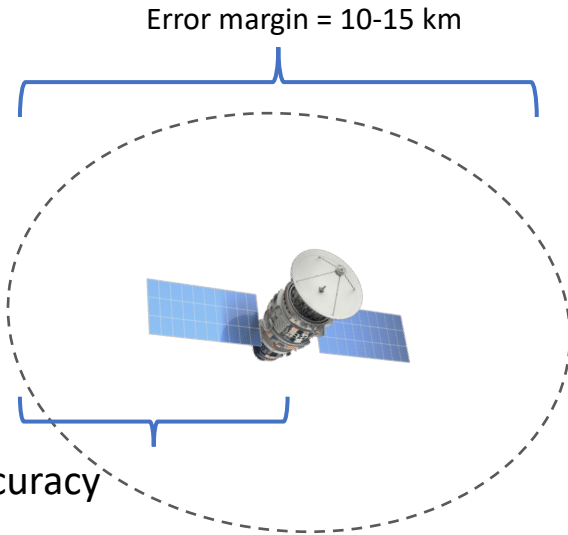
Example: Collision Avoidance in RPO

- Minimum data to share with other satellites
 - position, velocity, **covariance**



Stochastic systems

- Probabilistic, not deterministic
- Covariance matrices = quantify uncertainty
 - defined by ellipsoid
- Measure of TRUST, decisions based on accuracy



Problem: knowledge of error margins (covariance matrices) can lead to inferences on satellite capabilities, purpose, etc.

Solution: protect error margins using **privacy-preserving computation**



Privacy-Preserving Computation

Privacy-Preserving Computation (PPC)

- Allows for data to remain encrypted during computation
- Protects **physical integrity** of satellite during RPO and **data privacy** keeping data encrypted

Secure Multiparty Computation (SMC):

- Promising, well-developed method of PPC
- Cryptographic protocol that allows set of mutually-distrusting parties to jointly compute a function on their inputs, without revealing information about inputs (millionaire's problem)
- uses a) *garbled circuits* (2 parties) or b) *linear secret sharing* (>2 parties)

Linear Secret Sharing (LSS) scheme:

- keyless distributed encryption process.
- divides the “secret” (inputs) into randomly-generated shares and distributes to computing parties.



Background: What is SMC?

Secret Sharing

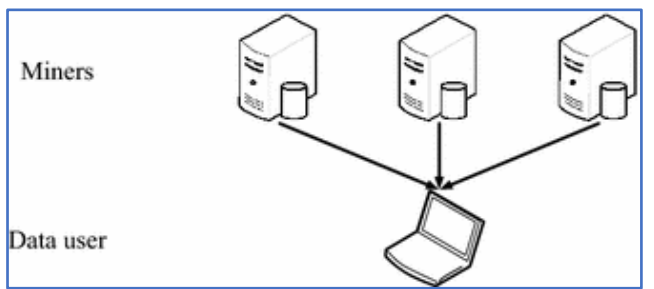
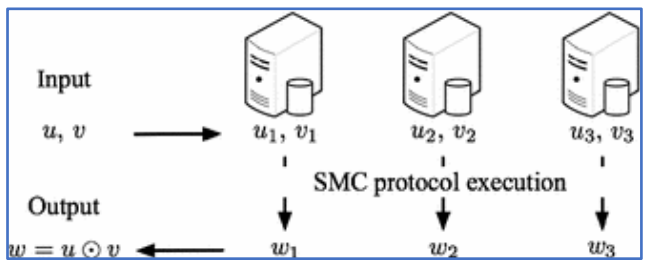
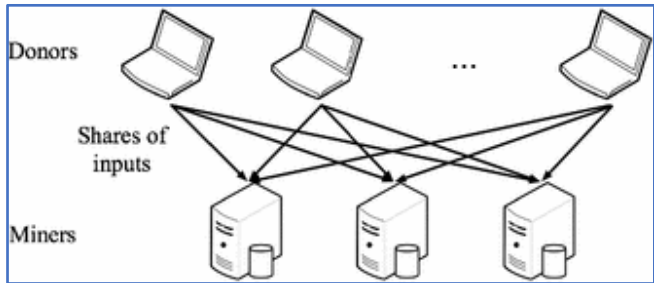
Distribute secret (input) among n parties, i.e. covariance matrices of 2 satellites. Predefined authorized subsets of n can reconstruct secret and return to user

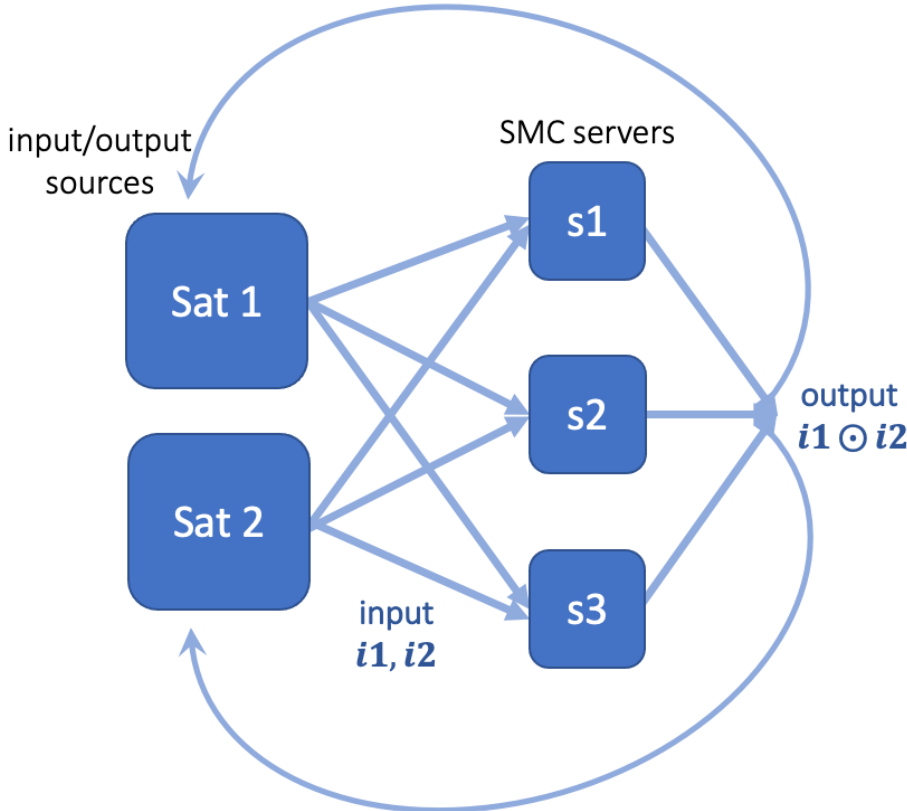
Threshold Secret Sharing

- k-out-of-n scheme
- secret S divided into n shares: $S = (s_1, \dots, s_n)$
 - S = element of finite field
 - shares = mapping to S + several random elements
- compromise of $k-1$ shares gives no info about S

Secret Sharing on Satellites

- Donors/data users = satellites participating in collision avoidance (at least 2)
- Miners = 3 computation servers
- Challenges: latency, bandwidth, small overhead on limited-resource system





Integrating SMC into satellite operations

- Testing different algorithms
 - Matrix multiplication
 - Artificial potential function
 - Attitude Optimization

Software toolkit

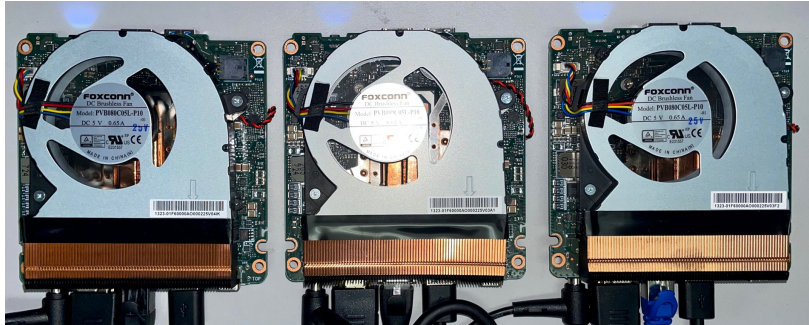
- Sharemind MPC platform
 - 3-party linear secret sharing
 - Provides host for SMC operations
 - System of libraries compatible with C/C++ and proprietary SecreC code



Methodology: hardware

Finding hardware for deployment in space

- Considerations:
 - Commercial off-the-shelf (COTS)
 - Sufficient radiation tolerance
 - Sufficient power & efficiency with limited resources
- Current findings:
 - NVIDIA TX2/nano boards (ARM processors)
 - AMD Ryzen embedded boards (x86 processors)



Hardware setup

Emulate satellite cluster

- Prototype with 3 Intel NUC boards
- Networked to communicate with each other
- 3 satellites minimum needed for SMC



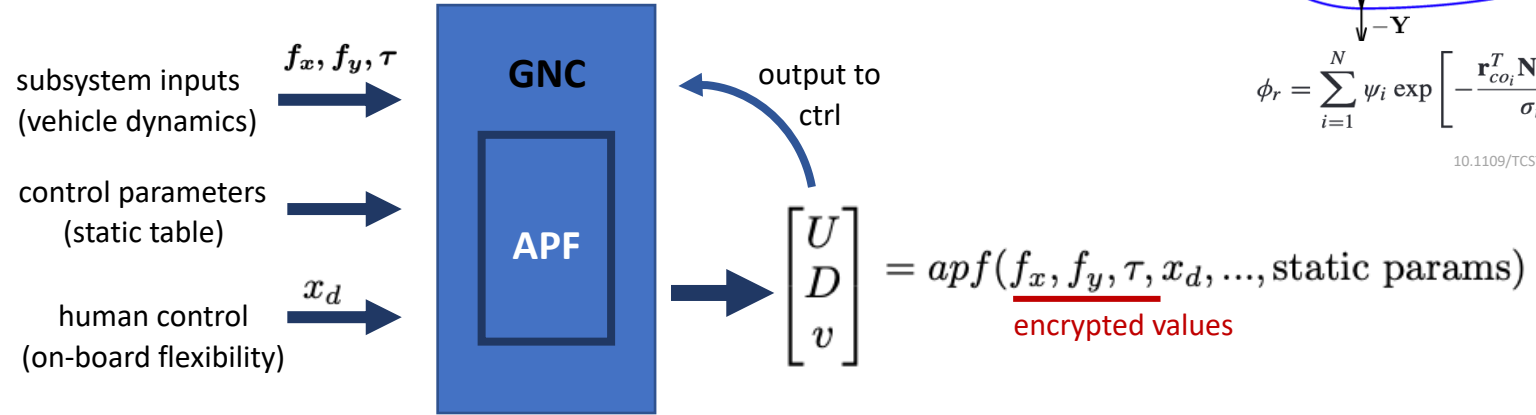
Cluster of satellites (Hawkeye 360)

Press Release, 2020. <https://www.he360.com/hawkeye-360-completes-milestone-in-preparation-to-launch-second-cluster/>

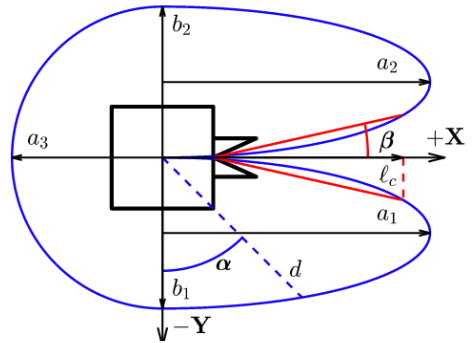


Another example: Artificial Potential Function (APF)

- Scenario: docking & collision avoidance at close range
 - On-board trajectory control
- Linear (relative) equations of motion



Keep-out zone potential



$$\phi_r = \sum_{i=1}^N \psi_i \exp \left[-\frac{\mathbf{r}_{coi}^T \mathbf{N}_i \mathbf{r}_{coi}}{\sigma_i} \right]$$

10.1109/TCST.2018.2866963

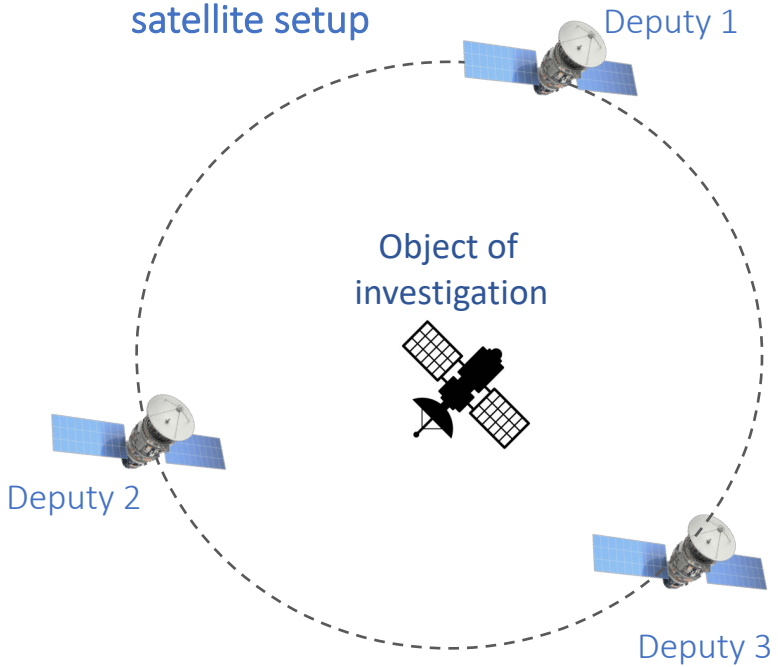


RPO example: Attitude Optimization

- Example scenario: inspecting downed satellite for sake of servicing, cooperation between satellites of different agencies/countries
- command torque to guide attitude of system to zero
- Blended cost approach:
 - Optimize **fuel & ending state**

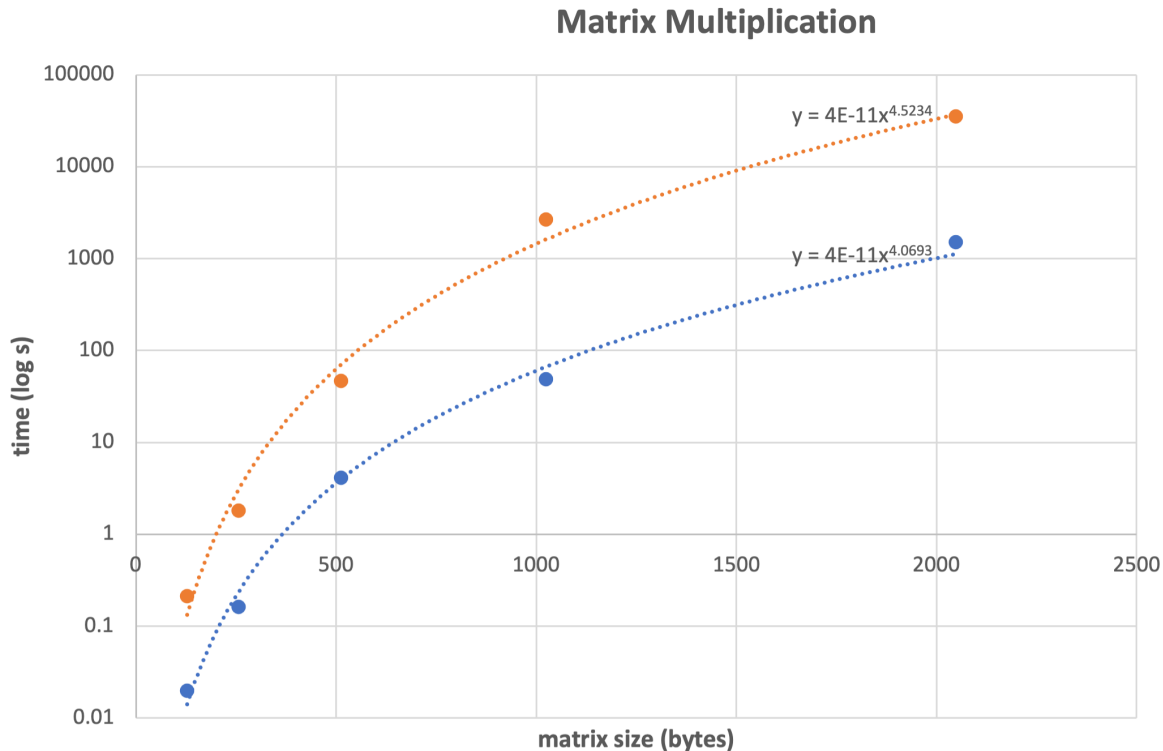
Privatized shared parameters

- Initial states: $\omega_1, \omega_2, \omega_3, v_1, v_2, v_3$
- Principle inertia: J, J_2, J_3

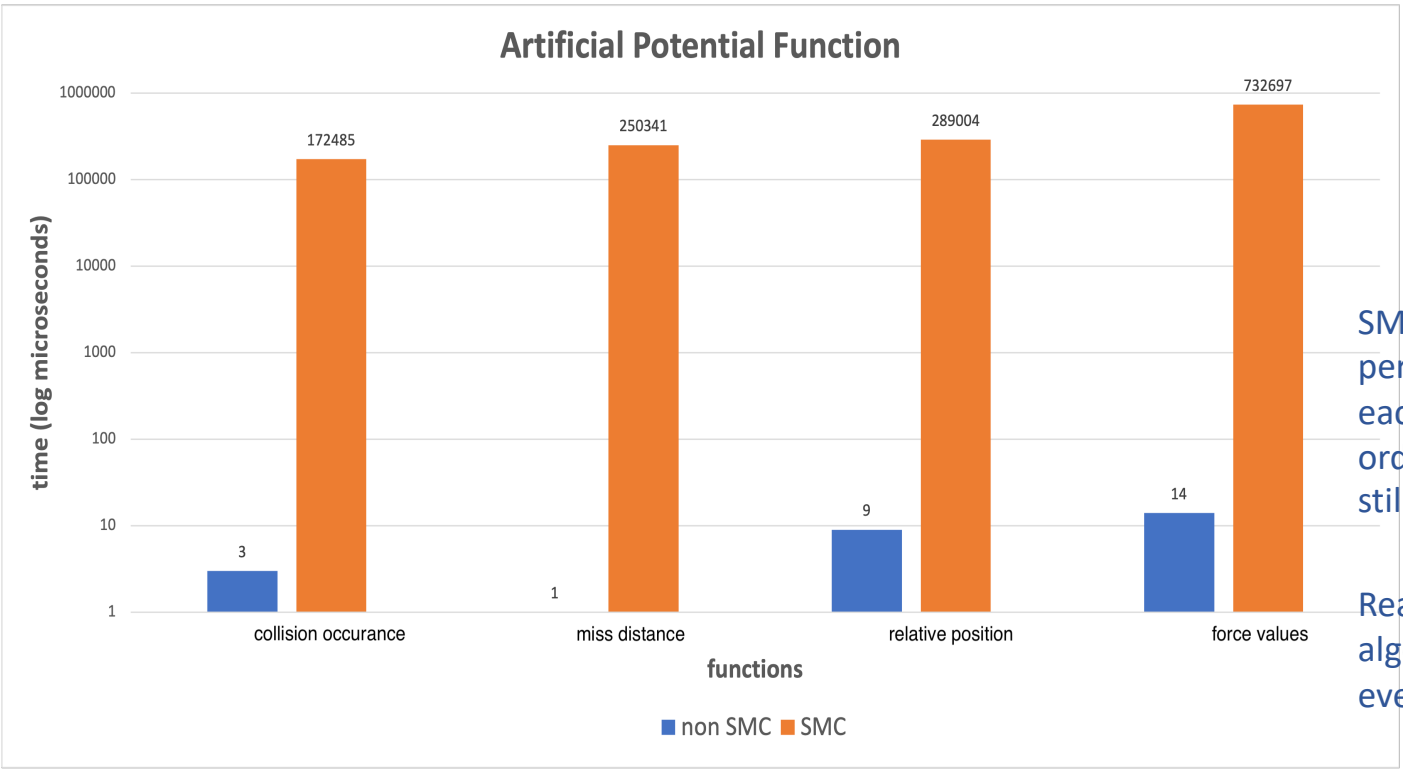




Evaluation: Matrix Multiplication



SMC increases time to perform algorithm on each matrix by 1-1.5 orders of magnitude



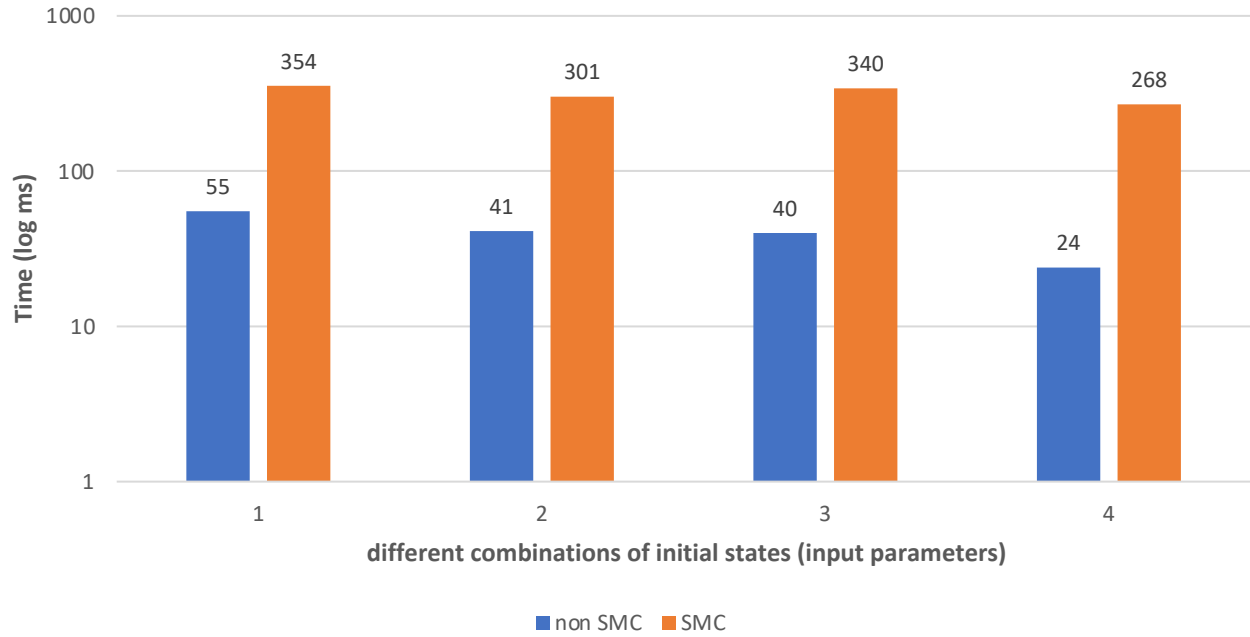
SMC increases time to perform algorithm on each function by 4-5 orders of magnitude, still < 1s to execute

Reasonable since algorithm refreshes every 30 sec– 15 min



Evaluation: Optimization

Attitude optimization



SMC increases time to perform algorithm on each function by ~1 order of magnitude

Algorithm refreshes every 10 seconds, still reasonable to use SMC



Results:

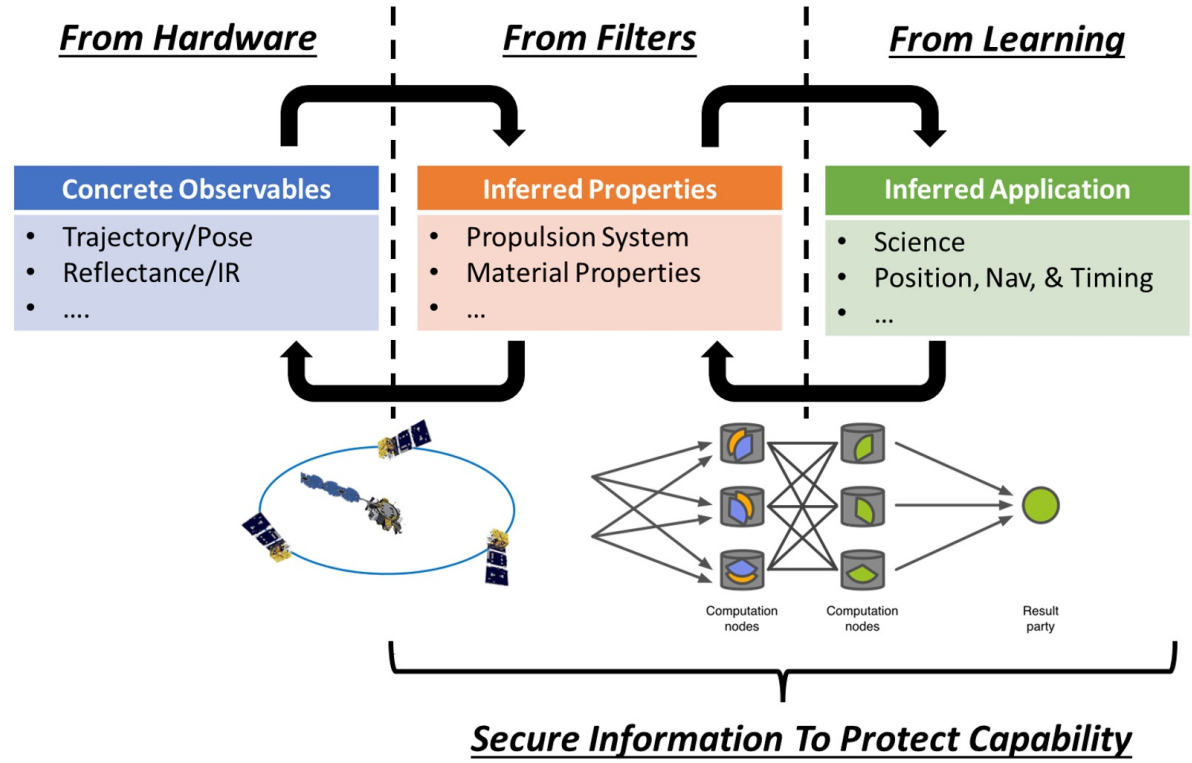
- SMC adds 1-1.5 orders of magnitude of overhead in matrix multiplication
- SMC adds 4-5 orders of magnitude in APF algorithm functions
 - Each operation is still <1 second in this environment, **promising for SMC in practice**
- SMC adds ~1 order of magnitude in attitude optimization code

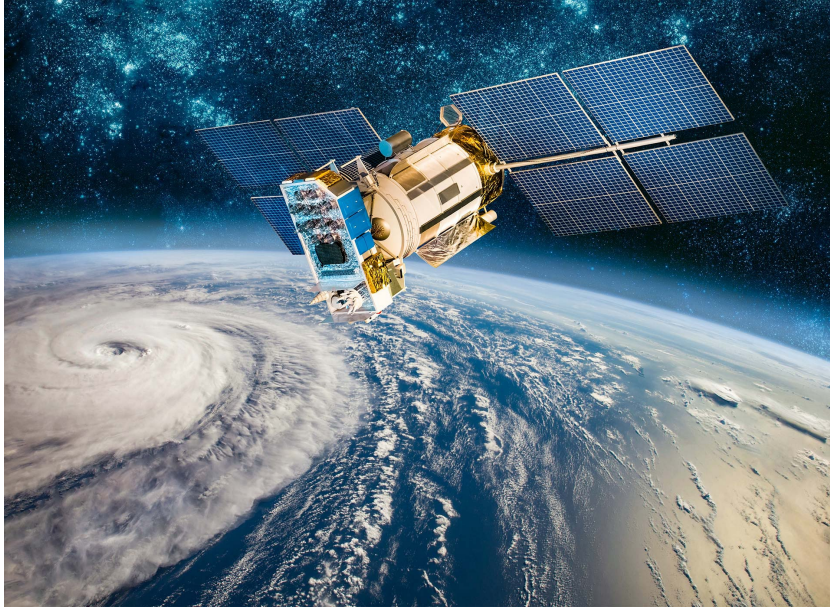
Next Steps:

- Test prototype on space-related hardware, i.e. NVIDIA and/or AMD boards
- Look into **efficiency** improvements
 - parallelization to increase efficiency
 - SIMD vectorization to improve scalability
- Investigate **characterization** problem beyond covariance matrices...



Characterization Problem





Source: verdict.co.uk

Action:

- Testing prototype of different satellite operations, specifically in RPO settings
- Integrating SMC into relevant space applications

Impact:

- Enhancing security in space, specifically problems where privacy is a concern
- Expanding applied cryptography/SMC to a new domain with these space applications



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